

Self-organisation of Knowledge in Socio-technical Systems: A Coordination Perspective

Stefano Mariani, Andrea Omicini

Università di Bologna

ISTC CNR

Rome, Italy

November 6th, 2015



- 1 Coordination Issues in STS
- 2 Tacit Messages and Perturbation Actions in Real-world STS
- 3 BIC, Stigmergy, and Smart Environments
- 4 Toward Self-organising Workspaces
- 5 *Molecules of Knowledge*
- 6 Conclusion
- 7 Outlook



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Challenges of Socio-technical Systems

- **Socio-technical systems** (STS) arise when *cognitive* and *social interaction* is mediated by *information technology*, rather than by the natural world (alone) [Whi06]
- STS are heavily *interaction-centred*, thus need to deal with **coordination** issues at the infrastructural level [MC94]
- Among the many coordination issues in STS are:
 - unpredictability** — “*humans-in-the-loop*” vs. software programmability and predictability
 - ⇒ coordination should account natively for *unpredictability* and *uncertainty*
 - scale** — *large-scale* distribution, openness, ever-increasing number of users, devices, data
 - ⇒ coordination should exploit *decentralised* mechanisms to scale in/out upon need

Challenges of Knowledge-intensive Environments

- **Knowledge-intensive Environments** (KIE) are workplaces in which *sustainability* of the organisation's long-term goals is *influenced* by the evolution of the body of *knowledge* embodied within the organisation itself [Bha01]
- Usually, KIE are computationally supported by STS, thus they need proper coordination too
- Among the many coordination issues in KIE are:
 - size** — *massive amount* of raw data, aggregated information, reification of procedures and best-practices, and the like
 - ⇒ coordination should minimise the *overhead* of information needed for coordination-related (non-) functional requirements
 - pace** — *high rate* of information production and consumption, huge frequency of interactions
 - ⇒ coordination mechanisms should be as *simple* and *efficient* as possible

A Path to Follow

Coordination models and technologies have already drawn inspiration from *natural systems*, looking for mechanisms enabling and promoting **self-organising** and **adaptive** coordination [VPB12, MZ09, VC09, ZCF⁺11, MO13]

A novel perspective

Similarly, we focus on the **human factor** in STS, seeking novel coordination approaches inspired by the latest *cognitive* and *social sciences* theories of *action* and *interaction*

The Approach

- 1 We *observed* real-world STS/KIE, analysing their (implicit) models of **action** and **interaction**
- 2 We *generalised* such models according to the theoretical framework of *Behavioural Implicit Communication* [CPT10], devising out **tacit messages** and **implicit actions** computationally exploited by such STS/KIE
- 3 We *conceived* the *M*olecules of *K*nowledge model [MO13], promoting *self-organisation of knowledge* in STS/KIE, inspired by the above framework and geared toward the notion of **self-organising workspace** [Omi11]

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Tacit Messages I

Tacit messages are introduced in [CPT10] to describe the kind of message a *practical action* (and its traces) may *implicitly* send to its observers:

- presence** — “Agent A is here”. Any agent (as well as the environment itself) observing any practical behaviour of A becomes aware of its existence — and, possibly, of contextual information, e.g., its location.
- intention** — “Agent A plans to do action β ”. If the agents’ workflow determines that action β follows action α , peers (as well as the environment) observing A doing α may assume A next intention to be “do β ”.
- ability** — “ A is able to do $\phi_{i \in \mathbb{N}}$ ”. Assuming actions $\phi_{i \in \mathbb{N}}$ have similar pre-conditions, agents (and the environment) observing A doing ϕ_i may infer that A is also able to do $\phi_{j \neq i \in \mathbb{N}}$.

Tacit Messages II

- opportunity** — “ $p_{i \in \mathbb{N}}$ is the set of pre-conditions for doing α ”. Agents observing A doing α may infer that $p_{i \in \mathbb{N}}$ hold, thus, they may take the opportunity to do α as soon as possible.
- accomplishment** — “ A achieved S ”. If S is the “state of affairs” reachable through action α , agents observing A doing α may infer that A is now in state S .
- goal** — “ A has goal g ”. By observing A doing action α , peers of A may infer A goal to be g , e.g. because action α is part of a workflow aimed at achieving g .
- result** — “Result R is available”. If peer agents know that action α leads to result R , whenever agent A does α they can expect result R to be soon available.

Tacit Messages in Real-world STS I

- We identified a set of (**virtual**) **practical actions**, fairly common in real-world STS despite the diversity in scope of each specific STS — e.g. Facebook vs. Mendeley¹ vs. Storify²
- For each, we point to a few *tacit messages* they may convey:
 - quote/share** — re-publishing or mentioning someone else's information can convey, e.g., tacit messages *presence*, *ability*, *accomplishment*. If X shares Y 's information through action a , every other agent observing a becomes aware of existence and location of both X and Y (*presence*). The fact that X is sharing information I from source S lets X 's peers infer X can manipulate S (*ability*). If X shared I with Z , Z may infer that X expects Z to somehow use it (*accomplishment*).

Tacit Messages in Real-world STS II

- like/favourite** — marking as relevant a piece of information can convey tacit messages *presence*, *opportunity*. If the socio-technical platform lets X be aware of Y marking information I as relevant, X may infer that Y exists (*presence*). If Y marks as relevant I belonging to X , X may infer that Y is interested in her work, perhaps seeking for collaborations (*opportunity*).
- follow** — subscribing for updates regarding a piece of information or a user can convey tacit messages *intention*, *opportunity*. Since X manifested interest in Y 's work through subscription, Y may infer X intention to use it somehow (*intention*). Accordingly, Y may infer the opportunity for collaboration (*opportunity*).

Tacit Messages in Real-world STS III

search — performing a search query to retrieve information can convey, e.g., tacit messages *presence*, *intention*, *opportunity*. If X search query is observable by peer agents, they can infer X existence and location (*presence*). Also, they can infer X goal to acquire knowledge related to its search query (*intention*). Finally, along the same line, they can take the chance to provide matching information (*opportunity*).

Now the question is

How to computationally exploit the envisioned *mind-reading* and *signification* abilities from a **coordination perspective**?

¹<https://www.mendeley.com>

²<https://storify.com>

Perturbation Actions I

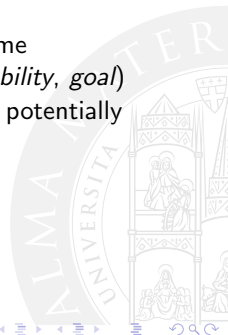
Perturbation actions are *computational functions* changing the state of a STS, in *response* to users' *interactions*, but *transparently* to them [MO15]

A possible answer is

Perturbation actions may then exploit the implicit information conveyed by tacit messages to leverage *mind-reading* and *signification* for **coordination purposes**

Perturbation Actions II

- Accordingly, perturbation actions may:
 - spread discovery messages informing agents about the presence and location of another (tacit message *presence*)
 - establish privileged communication channels between frequently interacting agents (*opportunity*)
 - undertake coordination actions enabling/hindering some desirable/dangerous interaction protocol (*intention, ability, goal*)
 - autonomously notify users about availability of novel, potentially interesting information (*accomplishment, result*)



Perturbation Actions in Real-world STS I

The virtual practical actions already identified are likely to (transparently) cause perturbation actions *under-the-hood*:

quote/share — provided by Facebook, Twitter (retweet), G+, LinkedIn, Mendeley (post), Academia.edu (publish), ResearchGate (publish), Storify, etc. It is likely to help the STS platform, underlying the social network application, in:

- suggesting novel connections
- ranking feeds in the newsfeed timeline

like/favourite — provided by Facebook, Twitter, G+ (+1), LinkedIn (suggest), Mendeley, Academia.edu (bookmark), ResearchGate (follow/download), Storify, etc. It is likely to influence the STS as above.

Perturbation Actions in Real-world STS II

follow — provided by Facebook (add friend), Twitter, G+ (add), LinkedIn (connect), Mendeley, Academia.edu, ResearchGate, etc. It is likely to help the STS platform by:

- suggesting further connections
- activating/ranking feeds in the newsfeed timeline

search — provided by almost every social network, it is the epistemic action by its very definition, thus may be exploited by the STS platform in a number of ways:

- re-organising the knowledge graph internally used by the STS
- tune the algorithm providing suggestions
- improve personalised advertising policies
- and many more...

A Systematic Analysis

... can we frame the above observations
within a

coherent computational framework

?

Of course we can.

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BIC in a Nutshell

Implicit interaction

Behavioural implicit communication (BIC) is a form of *implicit interaction* where no specialised signal conveys the message, since the message is the *practical behaviour* itself — and possibly, its post hoc *traces* [CPT10]

- BIC presupposes advanced **observation** capabilities: agents should be able to observe others' actions (and traces), as well as to *mind-read* the intentions behind them, so as to leverage *signification*
- BIC applies to human beings, to both cognitive and non-cognitive agents, and to *computational environments* as well [WOO07]
- Through BIC, such environments can become **smart environments**, namely pro-active, intelligent workplaces able to *autonomously adapt* their configuration and behaviour according to users' interactions [CPT10]

Cognitive Stigmergy in a Nutshell

Trace-based Communication

The notion of **stigmergy** has been introduced in the biological study of social insects [Gra59], to characterise how termites (*unintentionally*) coordinate themselves during nest construction, with no need of exchanging direct messages, but relying solely on *local* interactions instead

- Stigmergy is a special form of BIC, where the addressee does not directly perceive the behaviour, but just other *post-hoc traces* — in the form of **environment modifications**
- Such modifications are amenable of a **symbolic interpretation**, thus exploitable by agents featuring *cognitive* abilities — either humans or software
- When traces become signs, stigmergy becomes **cognitive stigmergy**, which involves agents able to correctly understand traces as signs *intentionally* left in the environment [Omi12]

Computational Smart Environments in a Nutshell

- In [TCR⁺05], an abstract model for computational *smart environments* is proposed, which defines two types of environment
 - c-env — **common environment**, where agents can observe only the state of the environment (including actions' traces), *not the actions* of their peers
 - s-env — **shared environment**, enabling different forms of *observability of actions*, and *awareness* of this observability
- Then, three requirements enabling them are devised
 - ① **observability** of agents' actions and traces should be enabled by default
 - ② the environment should be able to *understand* actions and their traces, possibly **inferring intentions** and goals motivating them
 - ③ agents should be able to understand the effects of their activity on the environment as well as on the other agents, so as to *opportunistically obtain a reaction*

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Putting All Together

- Quoting from [Omi11], a STS for working in knowledge-intensive environments requires

“that all the relevant information sources are made available to the user in a complete yet usable format, [...] that the working environment autonomously evolves and adapts to the individual uses and work habits”

- Furthermore,

“the main point here is the explicit representation, memorisation and exploitation of user actions in the workspace”

Our master equations

$\text{BIC} + (\text{cognitive}) \text{ stigmergy} = \text{Smart Environments}$

$\text{Smart Environments} + \text{Self-organisation} = \text{Self-organising Workspaces}$

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MoK in a Nutshell I

MoK

Molecules of Knowledge (*MoK*) is a coordination model promoting *self-organisation* of knowledge [MO13]

- Inspired to *biochemical tuple spaces* [VC09], *stigmergic coordination* [Par06], and *BIC* [CPT10]
- Main goals
 - 1 **self-aggregation** of information into more complex heaps, possibly reifying useful knowledge previously hidden
 - 2 **autonomous diffusion** of information toward the interested agents, that is, those needing it to achieve their goals

MoK in a Nutshell II

- A MoK-coordinated system is
 - a network of MoK **compartments** (*tuple-space* like information repositories)...
 - ... in which MoK **seeds** (*sources* of information) autonomously inject MoK **atoms** (*information* pieces)
 - atoms undergo *autonomous* and *decentralised* **reactions**
 - aggregate into **molecules** (*composite* information chunks)
 - **diffuse** to neighbourhoods
 - get **reinforced** and **perturbed** by users
 - decay as time flows
 - reactions are influenced by **enzymes** (reification of users' *epistemic actions*) and **traces** (their (*side*) *effects*)...
 - ...and scheduled according to Gillespie's **chemical dynamics** simulation algorithm [Gil77]

MoK Enzymes and Traces as BIC Enablers I

Model

$$\text{enzyme}(\text{species}, s, \text{mol})_c$$

$$\text{enzyme}(\text{species}, s, \text{mol}') + \text{mol}_c \xrightarrow{r_{\text{reinf}}} \text{enzyme}(\text{species}, s, \text{mol}') + \text{mol}_{c+s}$$

$$\text{trace}(\text{enzyme}, p, \text{mol})_c$$

$$\text{trace}(\text{enzyme}, p, \text{mol}') + \text{mol}_c \xrightarrow{r_{\text{pert}}} .\text{exec}(p, \text{trace}, \text{mol})$$

$$\text{enzyme} \xrightarrow{r_{\text{dep}}} \text{enzyme} + \text{trace}(\text{enzyme}, p[\text{species}], \text{mol})$$

species defines the **epistemic nature** of the action

s *strength* of reinforcement

p the *perturbation* the trace wants to perform

.exec starts execution of perturbation p^3

MoK Enzymes and Traces as BIC Enablers II

- Reinforcement *influences* relevance of information according to the (epistemic) nature and frequency of their actions and interactions
- Enzymes *situate* actions, e.g., at a precise time as well as in a precise space
- *Mind-reading* and *signification* are enabled by assuming that users manipulating a given corpus of information are interested in that information more than other
- Perturbation *influences* location, content, any domain-specific trait of information, according to users' inferred goals, with the goal of easing and optimising their workflows
- Traces enable the environment to exploit users' actions (possibly, inferred) *side-effects* for the profit of the coordination process — promoting the distributed collective intelligence leading to anticipatory coordination

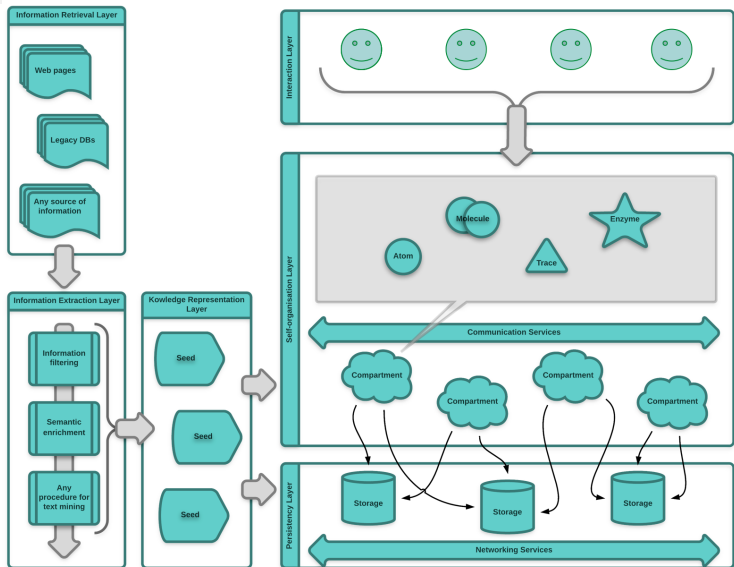
³Notice, p is implicitly defined by species, as highlighted by notation $p[\text{species}]$.

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MoK Ecosystem Architecture



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Simulated Scenario

- **Citizen journalism** scenario:

- users *share* a *MoK*-coordinated IT platform for retrieving and publishing news stories
- they have personal devices (smartphones, tablets, pcs, workstations), running the *MoK* middleware, which they use to *search* within the IT platform relevant information
- search actions can spread up to a *neighbourhood* of compartments — e.g., to limit bandwidth consumption, boost security, optimise information location, etc.
- search actions leave *traces* the *MoK* middleware exploits to *attract similar information*

Anticipatory coordination

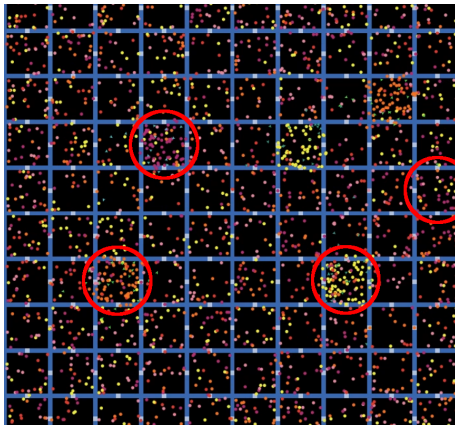


Figure: Whereas data is initially randomly scattered across workspaces, as soon as users interact clusters appear by emergence thanks to *BIC-driven self-organisation*. Whenever new actions are performed by catalysts, the *MoK* infrastructure *adaptively* re-organises the spatial configuration of molecules so as to better tackle the new coordination needs.

Discussion

- \mathcal{MoK} anticipates users' needs, not based on behaviour *prediction*, but on present actions and its *mind-reading* and *signification* abilities
 - addressing **unpredictability**
- \mathcal{MoK} reactions act only *locally*, thus exploit local information solely
 - addressing **scale**
- \mathcal{MoK} decay destroys information as *time* passes — furthermore, the *overhead* brought by \mathcal{MoK} is minimal, since it exploits solely information already in the system
 - addressing **size**
- \mathcal{MoK} reaction execution and BIC-related mechanisms are rather efficient, mostly due to their *local* nature and absence of complex *reasoning*
 - addressing **pace**

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Summing Up

- Engineering effective coordination for large-scale, knowledge-intensive STS is a difficult task
- Nature-inspired approaches proven successful in mitigating the issue, by leveraging self-organisation and adaptiveness
- We may further improve by shifting attention toward the social side of STS, transparently exploiting the epistemic nature of users' (inter-) actions for coordination purposes

The tools in our hands

BIC, (cognitive) stigmergy, and biochemical coordination give us the right models and approaches to do so

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A Bright and Exciting Future Awaits I

- The world needs *efficient* and *smart* ways of **preserving**, **managing**, and **analysing** the astonishing amount of knowledge it produces and consumes every day
- Big data approaches are more or less the standard now, mostly because they are good in finding *patterns* of knowledge, but:
 - they mostly fail in discovering *anti-patterns*, e.g., detecting outliers
 - they mostly fail in accommodating *ever-changing*, *heterogeneous* knowledge discovery needs
 - they mostly neglect “humans-in-the-loop”, relying on algorithms and measures (e.g. of similarity) which are completely *user-neutral* and *goal-independent*
 - they won't scale forever
 - they are not suitable for pervasive and privacy-demanding scenarios

A Bright and Exciting Future Awaits II

- We are in the perfect spot to start a paradigm shift toward **self-organising knowledge**, where:
 - **user-centric** adaptiveness of knowledge discovery processes is the foremost goal
 - measures and algorithms exploited for knowledge discovery, inference, management and analysis natively account for **users' goals**
 - seamlessly scale up/down/out/in naturally, being operating on the assumption that only **local-information** is available consistently
- As witnessed by the latest H2020 calls, increasingly demanding *user-inclusive* policy making, governance *participation*, *user-centric* knowledge sharing platforms, etc.
 - H2020-SC6-CO-CREATION-2016-2017
 - H2020-EINFRA-2016-2017
 - H2020-FETPROACT-2016-2017

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a-coordination-perspective](http://www.slideshare.net/andreaomicini/selforganisation-of-knowledge-in-sociotechnical-systems-a-coordination-perspective)

MoK

- On APICe

<http://mok.apice.unibo.it/>

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